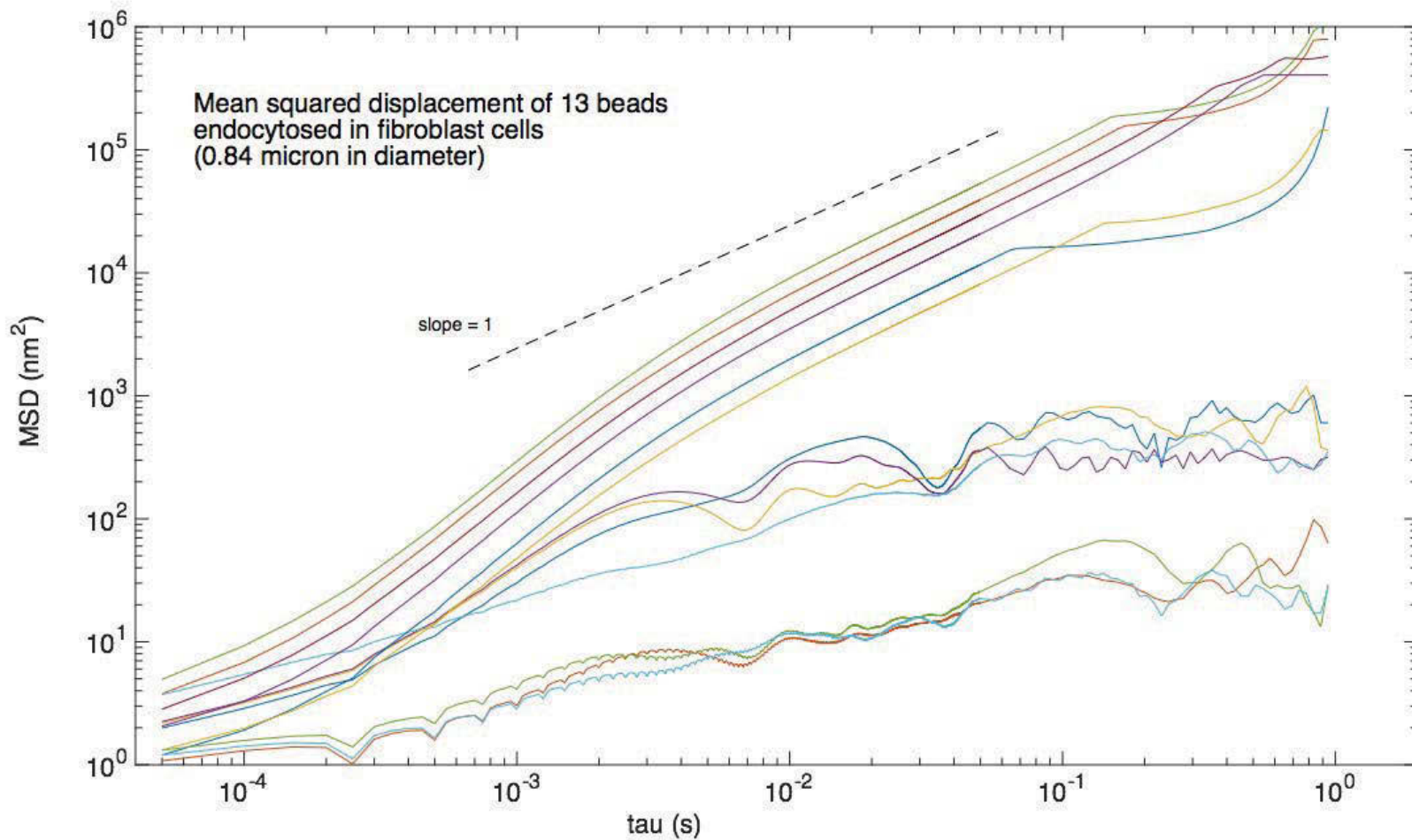


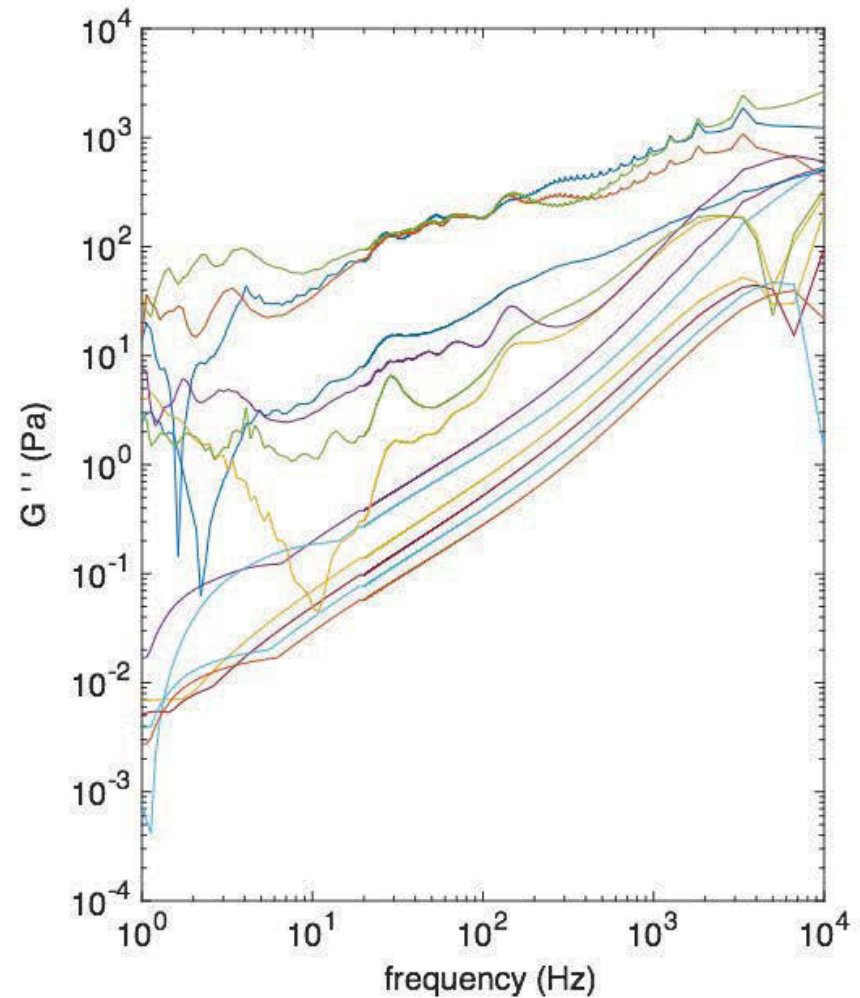
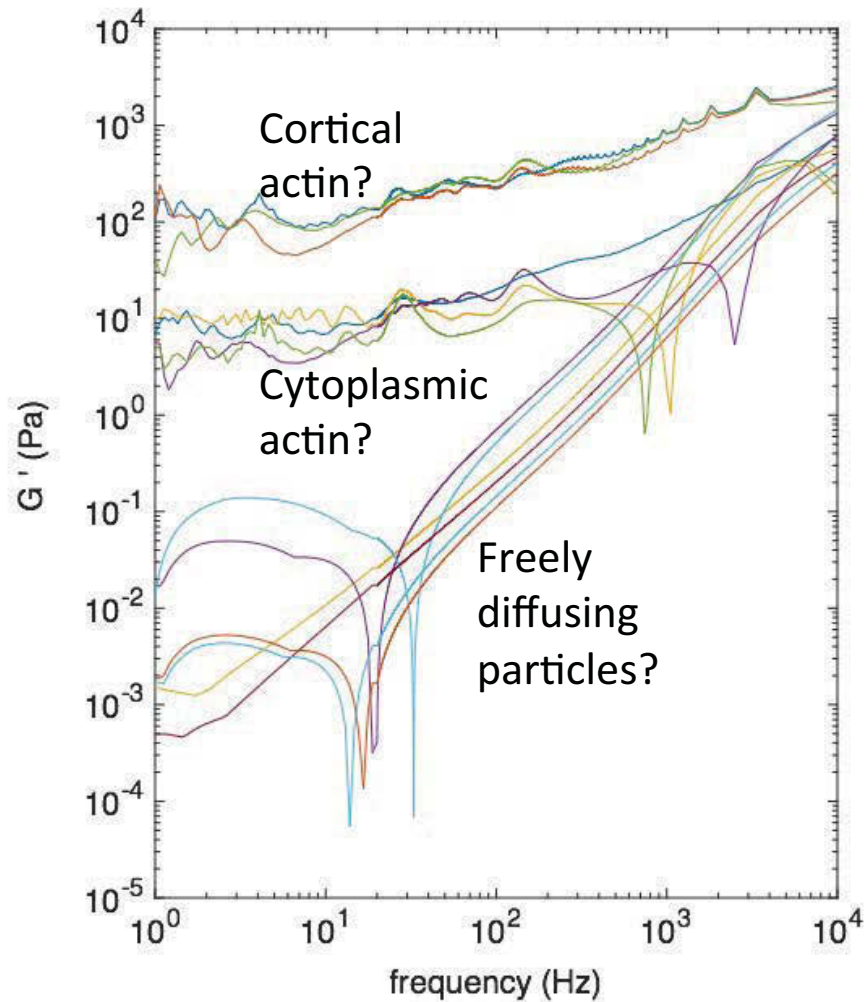
20.309 demo, 4/16/2015



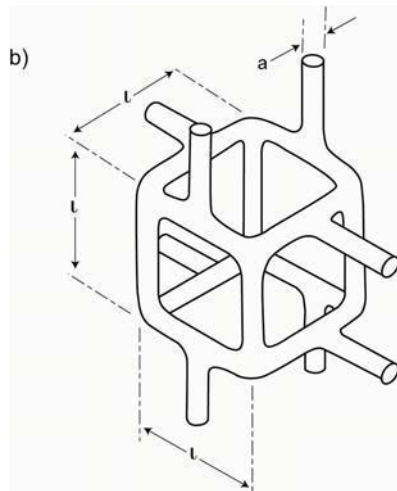
Generalized Stokes-Einstein Relation (an approximation):

$$|G^*(\omega)| \approx \frac{2k_B T}{3\pi a \langle \Delta R^2(\tau) \rangle \Gamma \left( 1 + \frac{d \ln \langle \Delta R^2(\tau) \rangle}{d \ln \tau} \right)}$$

### Storage and loss moduli

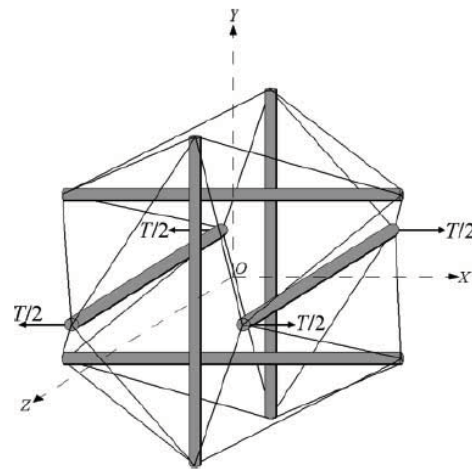


# Three microstructural models for the cytoskeleton



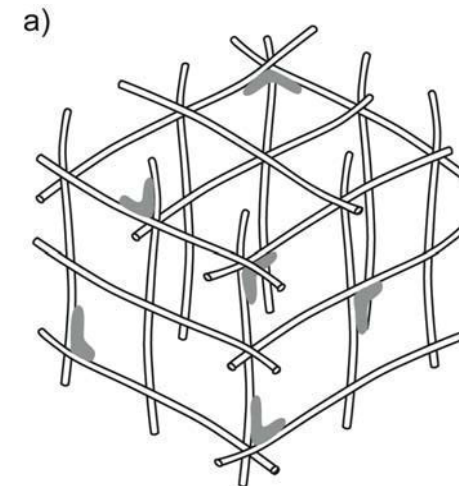
## Cellular solids

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## Tensegrity

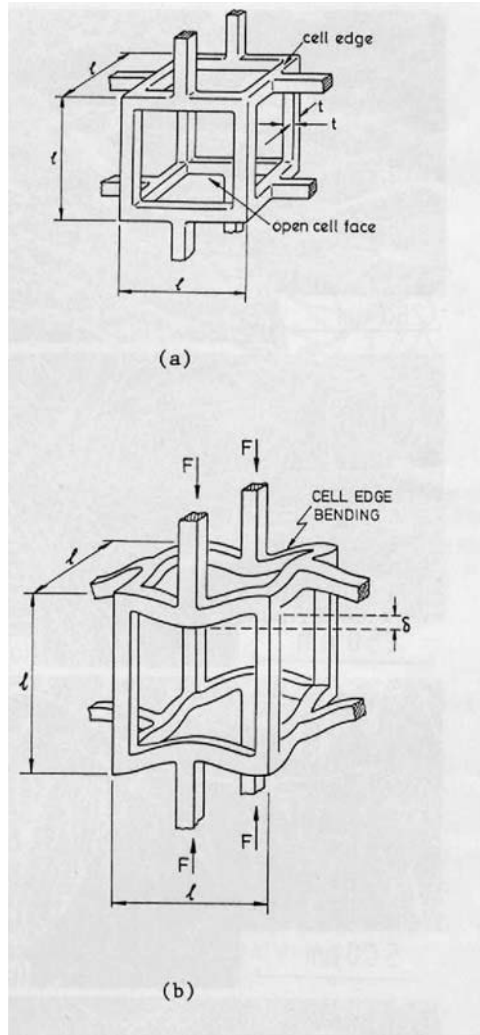
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Source: Stamenović, D., and Donald E. Ingber. "Models of Cytoskeletal Mechanics of Adherent Cells." *Biomechanics and Modeling in Mechanobiology* 1, no. 1 (2002): 95-108.



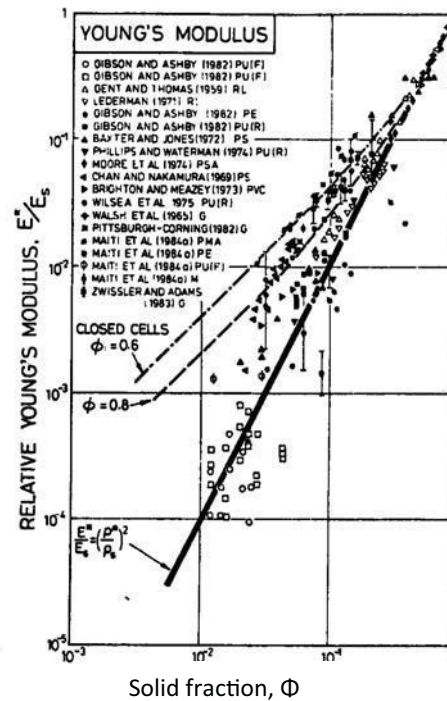
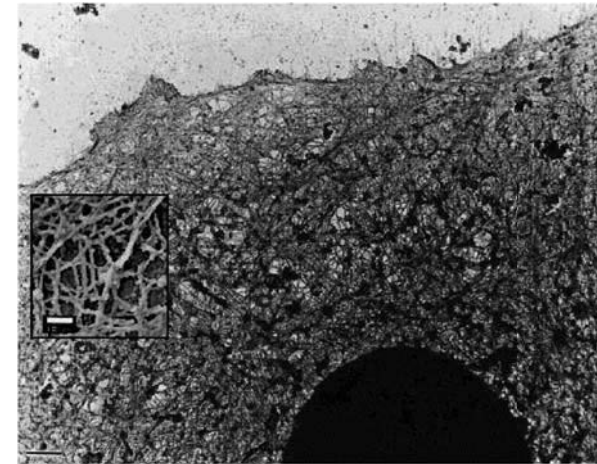
## Biopolymer

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# Cellular Solids Model



(Gibson & Ashby, 1988, Satcher & Dewey, 1997)



$$\Phi \sim (a/L)^2 \text{ (solid fraction)}$$

$$\delta \sim FL^3/(E_f I) \text{ from bending analysis}$$

where  $I \sim a^4$

$$\sigma \sim F/L^2$$

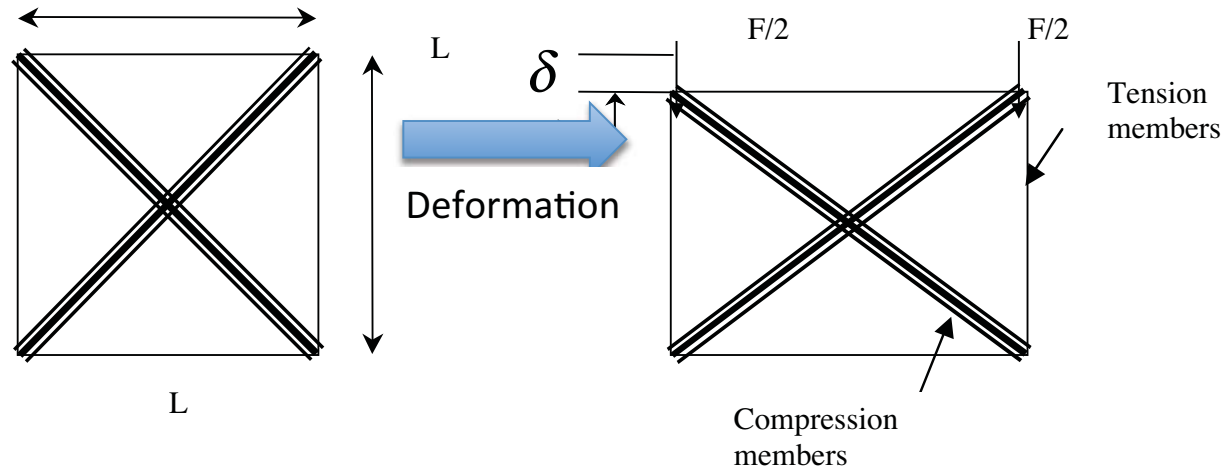
$$\varepsilon \sim \delta/L$$

$$E_n = \sigma/\varepsilon = c_1 E_f / L^4 \text{ (network modulus)}$$

$$E_n/E_f = c_1 \Phi^2 \text{ or } G_n \sim E_f \Phi^2$$

$$a = \text{radius of filaments}$$

# Tensegrity Model



$$U \sim \int_0^{L_1} \sigma_{f1} \epsilon_{f1} a^2 dx + \int_0^{L_2} \sigma_{f2} \epsilon_{f2} a^2 dx$$

Work done =  $\Delta$  (stored elastic energy)

$$F\delta \sim La^2 \left( \frac{\delta}{L} \right)^2 (2\sigma_{f0} + E_f)$$

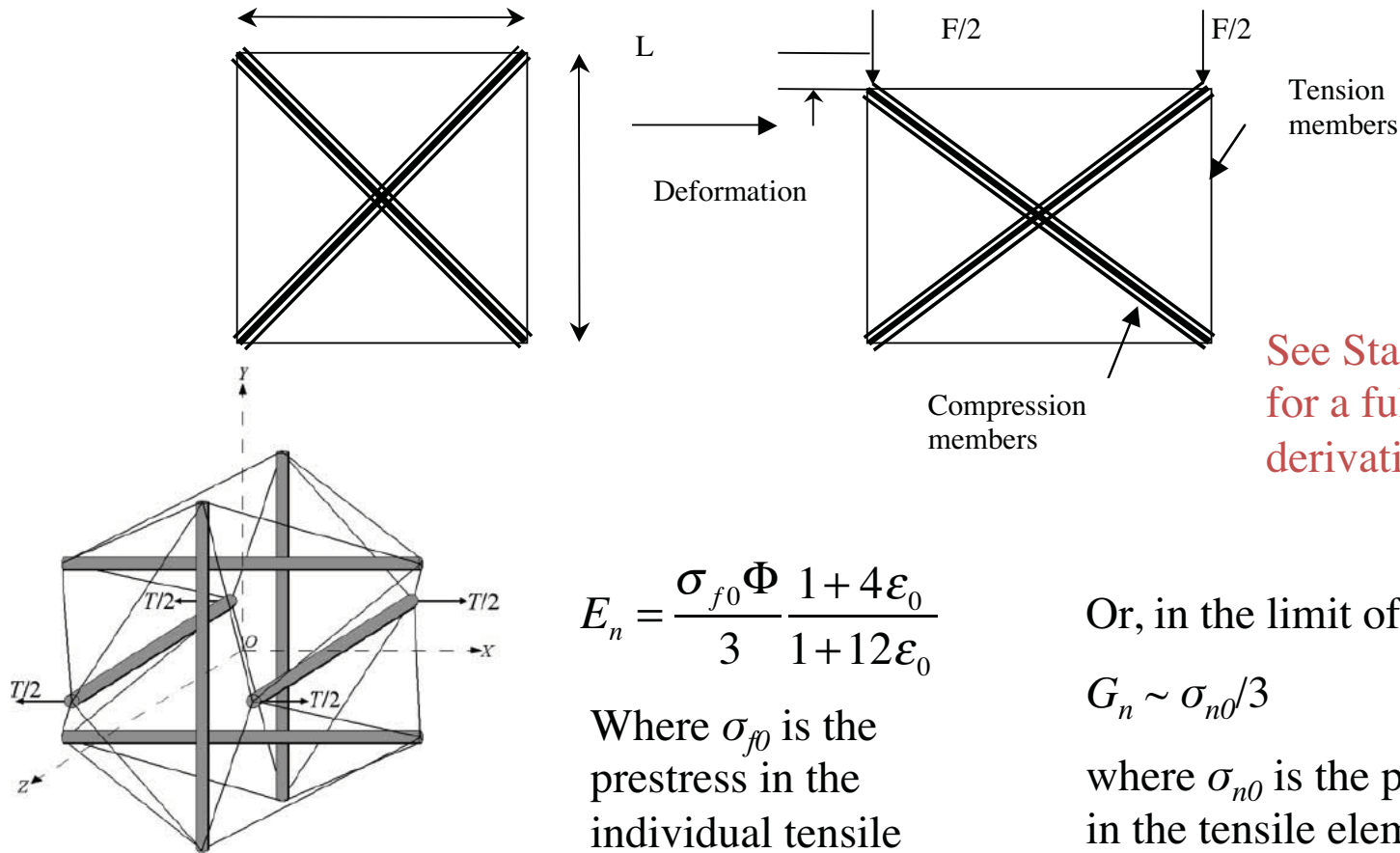
$$E_n \sim \frac{\sigma_n}{\delta/L} \propto (2\sigma_{f0} + E_f) \left( \frac{a}{L} \right)^2$$

$$\propto (2\sigma_{f0} + E_f) \Phi \propto 2\sigma_{n0} + E_f \Phi$$

Prestress contribution

Fiber modulus dependent contribution

# Tensegrity Model



See Stamenovic for a full derivation.

$$E_n = \frac{\sigma_{f0} \Phi}{3} \frac{1 + 4\varepsilon_0}{1 + 12\varepsilon_0}$$

Where  $\sigma_{f0}$  is the prestress in the individual tensile elements and  $\varepsilon_0$  is the initial strain in each.

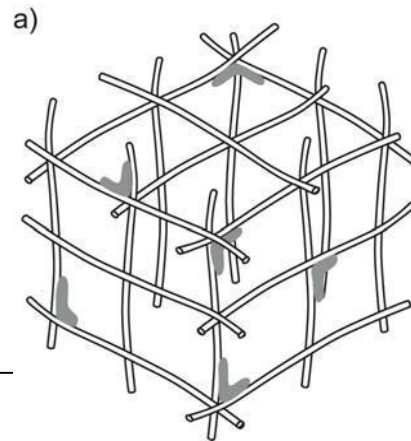
Or, in the limit of  $\varepsilon_0 \rightarrow 0$ ,

$$G_n \sim \sigma_{n0}/3$$

where  $\sigma_{n0}$  is the pre-stress in the tensile elements per unit total cross-sectional area ( $\sigma_{n0} = \pi\sigma_{f0}a^2/L^2$ ).

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 Source: Stamenović, D., and Donald E. Ingber. "Models of Cytoskeletal Mechanics of Adherent Cells." *Biomechanics and Modeling in Mechanobiology* 1, no. 1 (2002): 95-108.

# Biopolymer Models



For a single segment of polymer between cross-links (Isambert and Maggs, 1997, Maggs, 1999, Storm, et al., 2005)

$l_p$  = persistence length

$l$  = distance between entanglements or cross-links

$\xi$  = filament spacing (pore size)

$\epsilon_n$  = network strain

$E_n$  = network elastic modulus

$\delta$  = change in distance between entanglements/cross-links

$\Phi$  = solid fraction

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$$F = \frac{l_p}{l^4} K_b \delta$$

$$\epsilon_n = \frac{\delta}{l}$$

$$\sigma_n \sim F \cdot \frac{\text{filaments}}{\text{area}} \sim \frac{F}{\xi^2}$$

Low cross-link density

$$E_n = \frac{\sigma_n}{\epsilon_n} \sim \frac{l_p K_b}{l^3 a^2} \Phi$$

Maximum cross-link density ( $l \sim \xi$ )

$$E_n = \frac{\sigma_n}{\epsilon_n} \sim \frac{l_p K_b}{a^5} \Phi^{5/2}$$

# Scaling behaviors for the three models

## Tensegrity

Predicts a linear dependence on prestress

Athermal

No ability to change cross-link density

No role for cross-link mechanics

Viscoelasticity?

## Cellular Solids

Filament bending stiffness dominates

Maximal cross-link density

Athermal

No role for cross-link mechanics

Viscoelasticity?

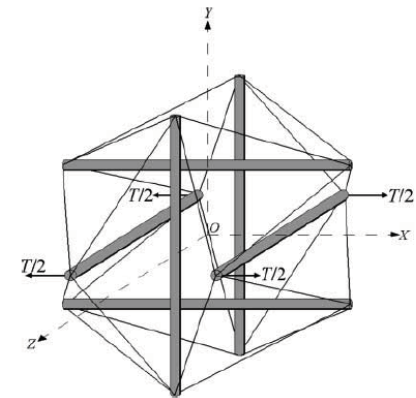
## Biopolymer

Thermal (WLC at high extensions)

Viscoelastic. Captures  $3/4$  power law at high frequency

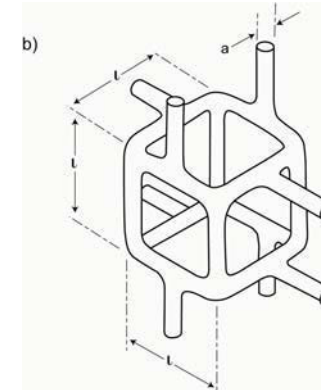
Cross-link density and mechanics?

$$G' \sim 2\sigma_{n0} + E_f \Phi$$

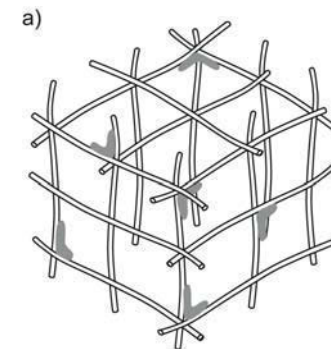


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$$G' \sim E_f \Phi^2$$



$$G' \sim K_b^2 \Phi^1 \rightarrow K_b^2 \Phi^{5/2}$$

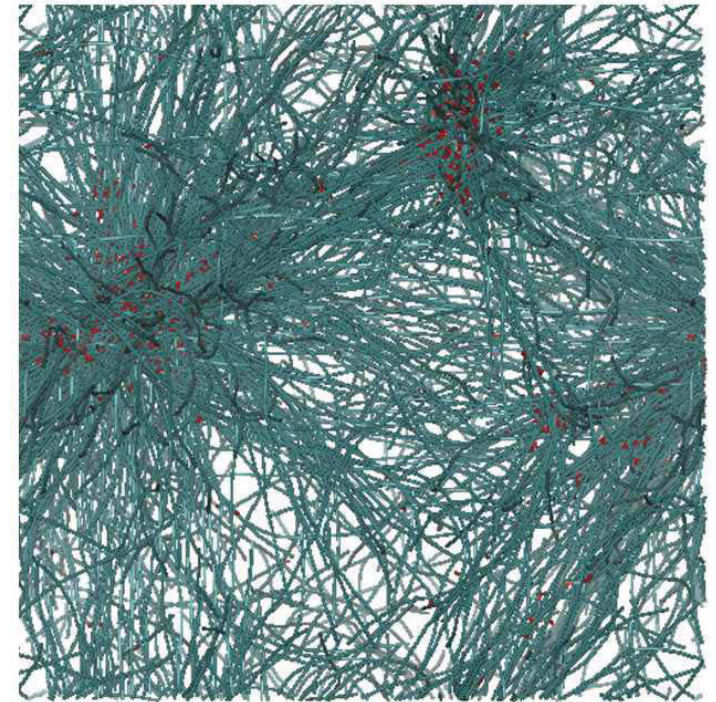


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# Computational Models of the Cytoskeleton

- Individual monomers and cross-linking proteins self assemble into a 3D network
- Motors can be added to simulate the effects of myosin II
- Networks are thermally active, fully 3D and exhibit many of the characteristics of cells and actin gels
- Mechanical properties such as  $G'$ ,  $G''$  and generated internal stress can be readily computed.



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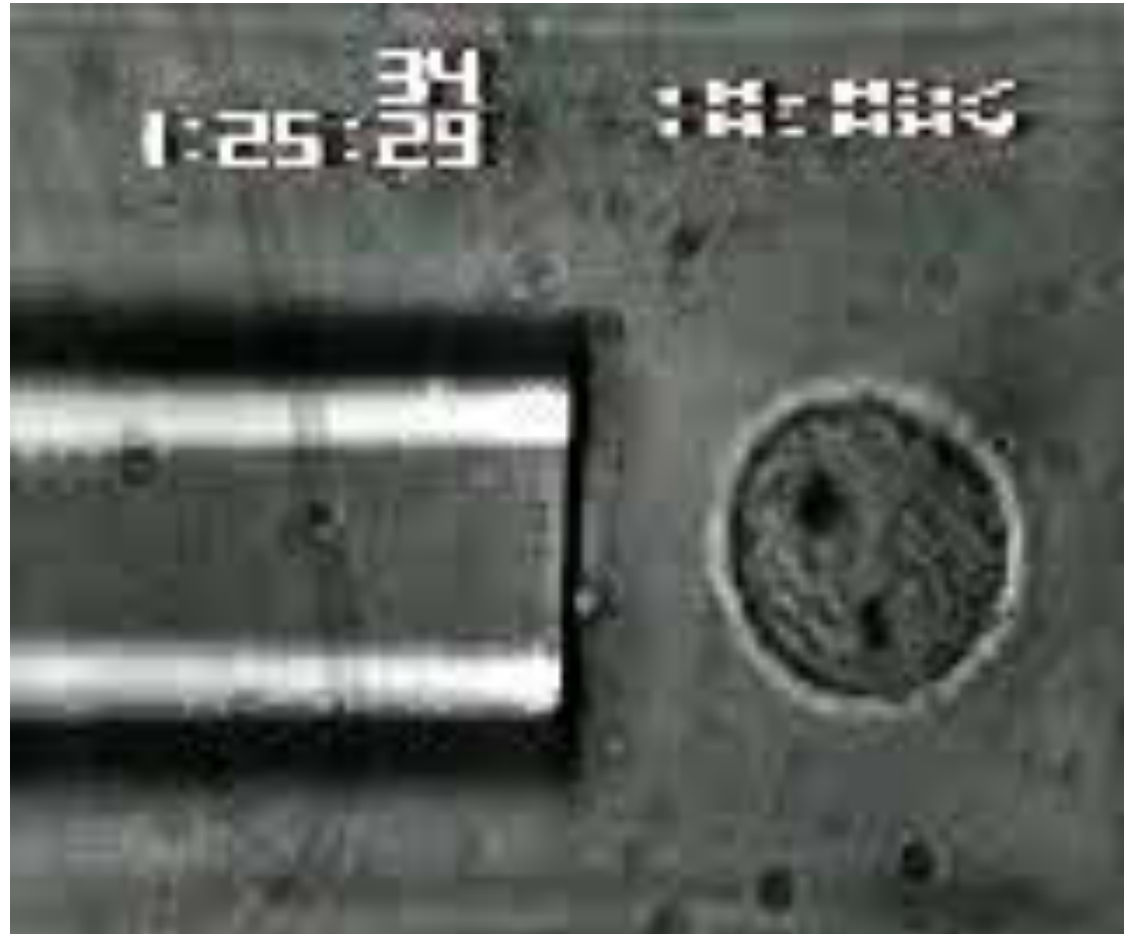
# Take home messages

- Cells exhibit a weak power-law rheology
- With increasing strain: linear, strain-stiffening, strain softening
- Fluidization (role of cross-links?)
- Simulations show that tensed networks are consistent with much of the observed static behavior
- Cytoskeletal networks behave athermally, and cross-link rupture appears to be more important than unfolding in network fluidization and remodeling
- Motor activity is a significant determinant of network morphology
- Motors induce prestress and thereby actively control cytoskeletal stiffness

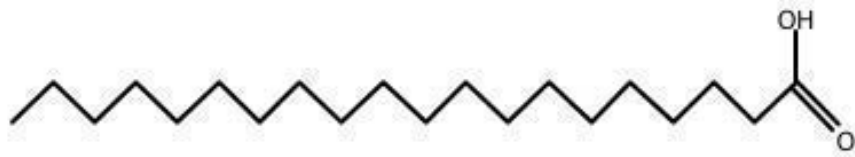
# Membrane mechanics:

## Micropipette Aspiration

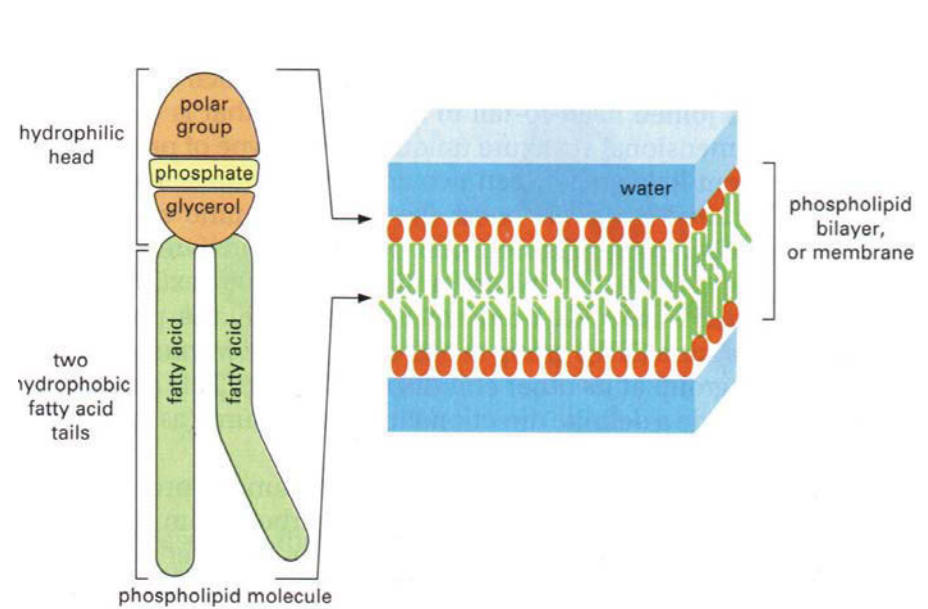
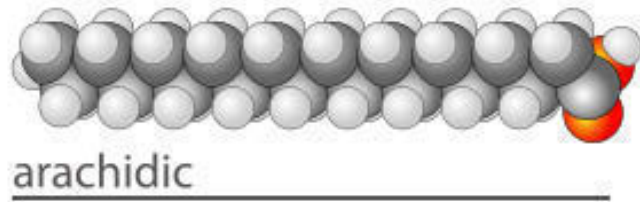
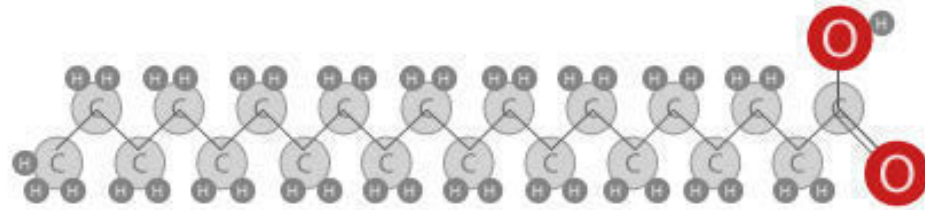
Measurements suggest a model consisting of a viscous core and a membrane of constant surface tension.



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A fatty acid molecule (left)  
and aggregation of phospholipids  
to form a cell membrane (below)



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Attractive: hydrophobic tails.

Repulsive: hydrophilic heads, ionic groups, steric effects.

B. Alberts et al. (2004)

Figure 11-4 removed due to copyright restrictions.

Source: Nelson, David L., et al. *Lehninger Principles of Biochemistry*. Macmillan, 2008.

D. L. Nelson and M. M. Cox (2005)

Image of lipid bilayer removed due to copyright restrictions.

H. Lodish et al. (2004)

# Lipid bi-layer characteristics

Figure 11-1 removed due to copyright restrictions.

Source: Nelson, David L., et al. *Lehninger Principles of Biochemistry*. Macmillan, 2008.

Thickness ~ 5 nm

Normal (resting) tension ~ 0.01 mN/m

Maximum areal strain ~4%

Rupture tension ~10 mN/m

(Surface tension of water ~ 70 mN/m)

(1 mN/m = 1 dyn/cm)

D. L. Nelson and M. M. Cox (2005)

# Red blood cells (erythrocytes)

Uniform, disc-shaped normal  
erythrocyte      →



## Red Blood Cells

Illustration courtesy of [Blausen.com](https://www.blausen.com) staff. "Blausen Gallery 2014". Wikiversity Journal of Medicine. DOI:10.15347/wjm/2014.010. ISSN 20018762. CC license BY.

Images of red blood cell membrane removed due to copyright restrictions.  
Source: Alberts, B., et al. *Molecular Biology of the Cell*. 4th ed. Garland Science, 2002.

Molecular Biology of the  
Cell, Bruce Alberts, Dennis  
Bray, Julian Lewis, Martin  
Raff, Keith Roberts, James  
D. Watson © 1994

# White blood cells (leukocytes)

Images removed due to copyright restrictions.

Scanning electron micrographs showing a) an intact "passive" neutrophils with many membraneous folds and microvilli and b) a neutrophil that has been treated with 4 M-5M Triton-X to dissolve away the membrane and leave the underlying cytoskeleton in the exposed cortical region.

<http://mems.egr.duke.edu/Faculty/rhochmuth.html>



# Homogeneous??

## Cells in 3D matrix

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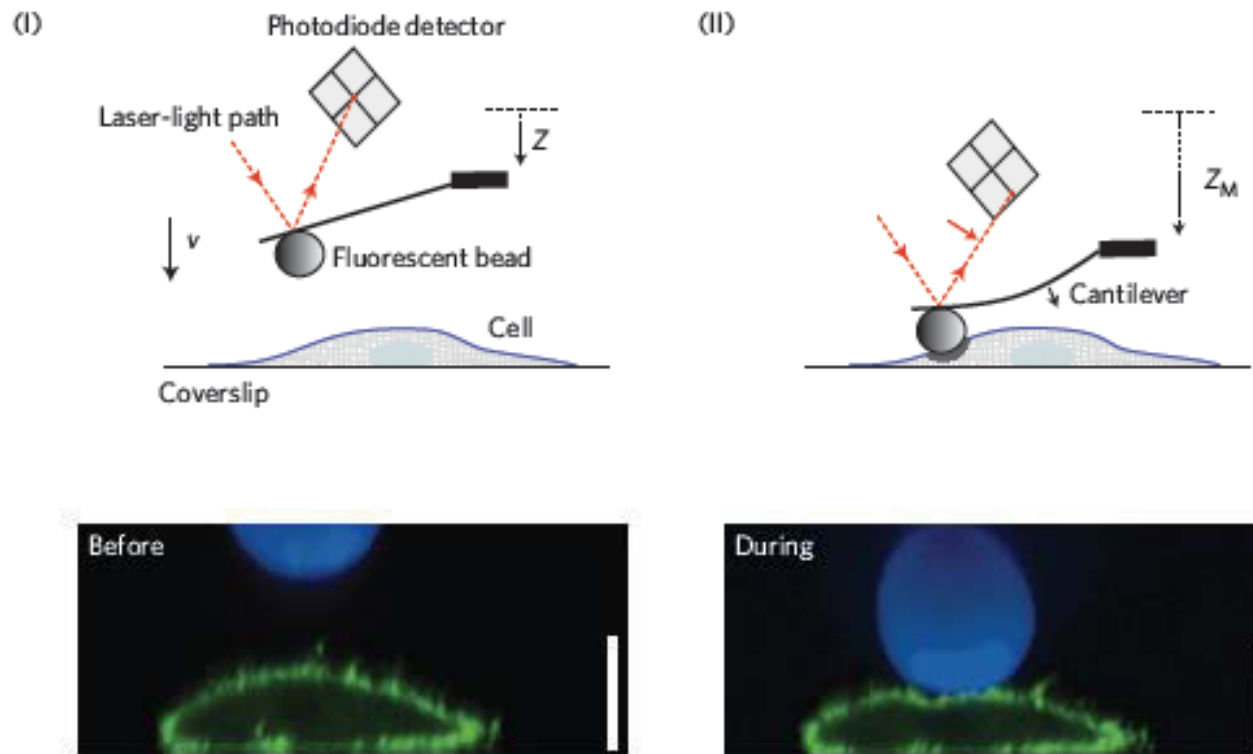
MDA-MB-231 breast cancer cells migrating inside a collagen gel.

- Dense cortical actin with myosin.
- Cross-linkers more homogeneously distributed

Rajagopalan, unpublished

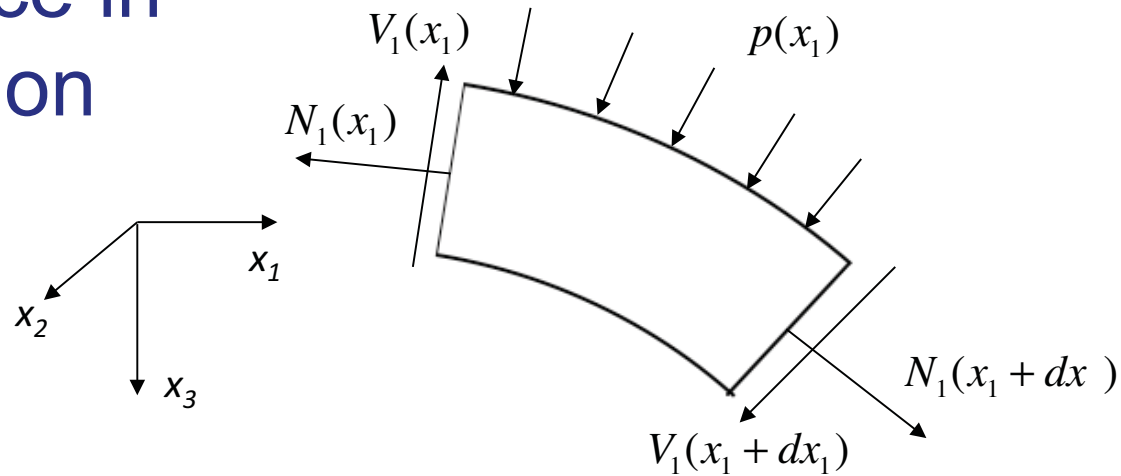
# Indentation by a microsphere

## Importance of the cortex



Courtesy of Macmillan Publishers Limited. Used with permission.  
Source: Moendarbary, Emad, et al. "The Cytoplasm of Living Cells Behaves as a Poroelastic Material." *Nature Materials* 12, no. 3 (2013): 253-61.

# Force balance in the $x_3$ direction



$$V = \int_0^h \sigma_{13} dx_3$$

$$p dx_1 - V_1(x_1) - N_1(x_1)\theta(x_1) + V_1(x_1 + dx_1) + N_1(x_1 + dx_1)\theta(x_1 + dx_1) = 0$$

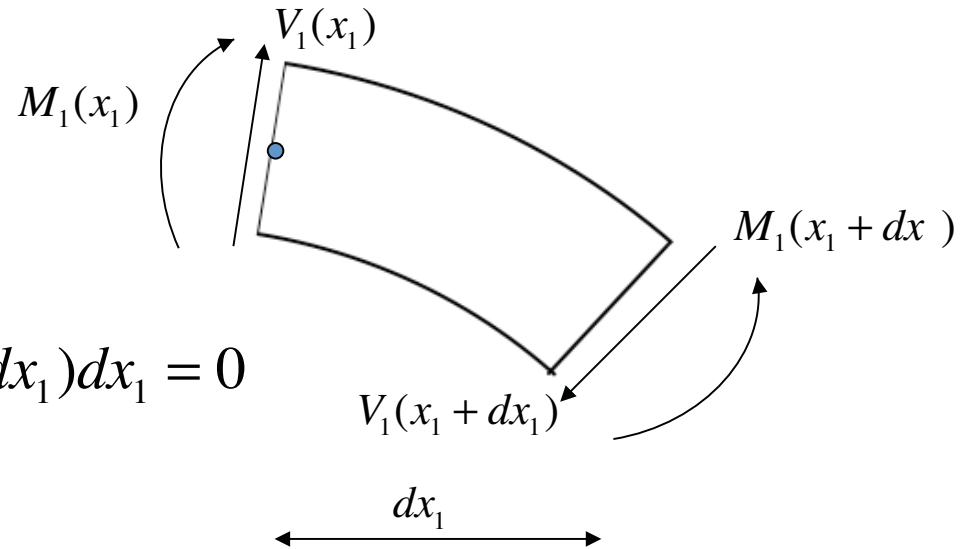
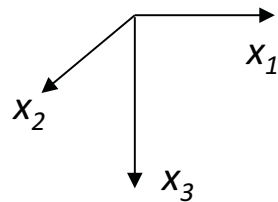
Use Taylor expansions for  $V_1$  and  $N_1\theta_1$

$$V_1(x_1 + dx_1) = V_1(x_1) + \frac{\partial V_1}{\partial x_1} dx_1$$

Combine and divide by  $dx_1$ :

$$p(x_1) + \frac{\partial V_1}{\partial x_1} + \frac{\partial}{\partial x_1}(N_1\theta_1) = p(x_1) + \frac{\partial V_1}{\partial x_1} + \frac{\partial}{\partial x_1} \left[ N_1 \left( \frac{\partial u_3}{\partial x_1} \right) \right] = 0$$

# Moment (torque) balance about the $x_2$ axis



$$-M_1(x_1) + (M_1 + \frac{\partial M_1}{\partial x_1} dx_1) - V_1(x_1 + dx_1) dx_1 = 0$$

$$\frac{\partial M_1}{\partial x_1} = V_1(x_1)$$

$$M_1(x_1) = -K'_b \frac{\partial^2 u_3}{\partial x_1^2}$$

$$p - K'_b \frac{\partial^4 u_3}{\partial x_1^4} + \frac{\partial}{\partial x_1} \left( N_1 \frac{\partial u_3}{\partial x_1} \right) = 0$$

in 1D

Full governing equations for linear deformations, and the reduced forms for bending or tension dominance

Bending stiffness

Membrane tension

$$K'_b \left( \frac{\partial^4 u_3}{\partial x_1^4} \right) - N \left( \frac{\partial^2 u_3}{\partial x_1^2} \right) - p = 0$$

$$\frac{\text{Bending}}{\text{Tension}} \propto \frac{K'_b \bar{u} / \lambda^4}{N \bar{u} / \lambda^2} \propto \frac{K'_b}{N \lambda^2} \gg 1$$

$$\frac{K'_b}{N \lambda^2} \ll 1$$

$$K'_b \left( \frac{\partial^4 u_3}{\partial x_1^4} \right) = p$$

$$p = -N \left( \frac{\partial^2 u_3}{\partial x_1^2} \right) \cong N \left( \frac{1}{R} \right)$$

u = displacement

p = pressure difference

N = membrane tension

R = radius of curvature

x = spatial coordinate

λ = characteristic length

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